

```
int a,b,c,d;

void setup()
{
  pinMode(2,INPUT);
  pinMode(3,INPUT);
  pinMode(13,OUTPUT);
  Serial.begin(115200);
  a = 2;
  b = 3;
}

void loop()
{
  //Serial.print(digitalRead(2));
  //Serial.println(digitalRead(3));

  if(digitalRead(3)==0)
  {
    Serial.println("Motor STOP");
    digitalWrite(13,1);
  }
  else
  {
    Serial.println("Motor START");
    digitalWrite(13,1);
  }
  delay(100);
}
```