

```
void setup()
{
    pinMode(2, INPUT);
    pinMode(3, INPUT);
    pinMode(13, INPUT);
    Serial.begin(115200);
    int a = 3;
    int b = 5;
}
```

```
void
loop()
{
    if(digitalRead(3)==0)
    {
        Serial.println("Motor STOP");
        digitalWrite(13, 0);
    }
    else if(digitalRead(2)==0)
    {
        Serial.println("Motor START");
        digitalWrite(13, 1);
    }
    delay(100);
}
```