

```
int  a,b,c,d;

void  setup()
{
pinMode(2,INPUT);
pinMode(3,INPUT);
pinMode(13,OUTPUT);
Serial.begin(115200);
a = 2;
b = 3;
}

void  loop()
{
    //Serial.print(digitalRead(2));
    //Serial.println(digitalRead(3));

if(digitalRead(3)==0)
{
Serial.print("Moter  STOP");
digitalWrite(13,0);
}
else if  (digitalRead(2)==0);
{
Serial.print("Motor  STOP");
digitalWrite(13,1);
}
delay(100);

}
```