

```
int  a,b,c,d;

void  setup()
{
    pinMode(2,INPUT);
    pinMode(3,INPUT);
    pinMode(13,OUTPUT);
    Serial.begin(115200);
    a = 2;
    b = 3;
}

void  loop()
{
    //Serial.print(digitalRead(2));
    //Serial.println(digitalRead(3));

    if(digitalRead(3)==0)
    {
        Serial.print("Motor  STOP");
        digitalWrite(13,0);
    }
    else  if(digitalRead(2)==0);
    {
        Serial.print("Motor  STOP");
        digitalWrite(13,1);
    }

    delay(100);
}
```