

```
int  a,b,c,d;
```

```
void  setup()
```

```
{  
  pinMode(2,INPUT);  
  pinMode(3,INPUT);  
  Serial.begin(115200);  
  a=5;  
  b=3;  
}
```

```
void  loop()
```

```
{  
  if(digitalRead(3)==0)  
{  
    Serial.println("Motor  STOP");  
    digitalWrite(13,0);  
  }  
  else if (digitalRead(2)==0)  
  {  
    Serial.println("Motor  START");  
    digitalWrite(13,1);  
  }  
  delay(100);  
}
```