

```
int a,b,c,d;
```

```
void setup()
```

```
{
```

```
pinMode(2, INPUT);
```

```
pinMode(3, INPUT);
```

```
pinMode(13, OUTPUT);
```

```
Serial.begin(115200);
```

```
a=2;
```

```
b=3;
```

```
}
```

```
void loop()
```

```
{
```

```
if (digitalRead(3)==0)
```

```
{
```

```
Serial.println("Motor StOP");
```

```
digitalWrite(13, 0);
```

```
}
```

```
else if (digitalRead(2)==0)
```

```
{
```

```
Serial.println("Motor START");
```

```
digitalWrite(13, 1);
```

```
}
```

```
delay(100);
```

```
}
```