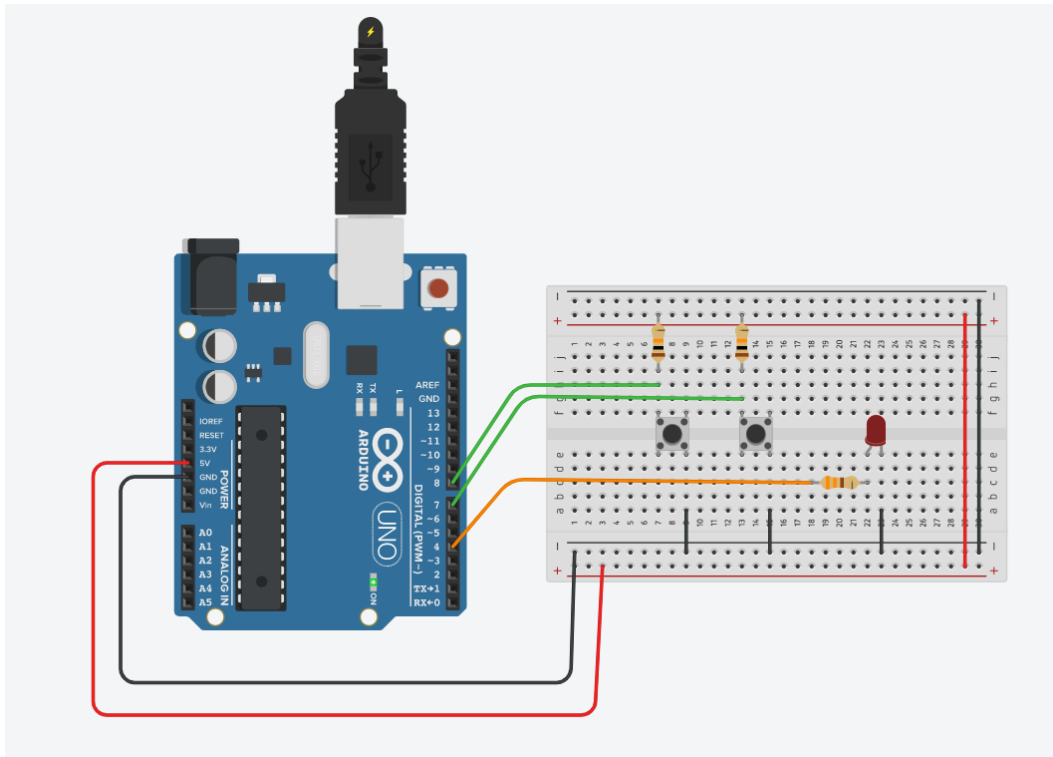




การต่อวงจร

```
1 // C++ code
2 //
3 int Motor,start,stop;
4 void setup()
5 {
6   pinMode(7,INPUT);
7   pinMode(8,INPUT);
8   pinMode(4,OUTPUT);
9 }
10
11 void loop()
12 {
13   start = digitalRead(8);
14   stop = digitalRead(7);
15   if(stop == 0)
16   {
17     Motor = 0;
18   }
19   else if(start == 0)
20   {
21     Motor = 1;
22   }
23   digitalWrite(4,Motor);
24 }
```

คำสั่ง